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Examiner Initials*	Cite No.1			
/MW/	Historia at al. Il Construction			
/MW/		Hyon et al.; "Dynamics-Based Control of a One-Leggad Hopping Robot;" Proc. Instr. Mech. Engrs. Vol . 217, Part I; J. Systems and Control Engineering; 105502; IMechE 2003; January, 2003; pages 83-98		
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Examiner	Maria Maiakanti	Date	
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/MW	1	Zeglin et al.; "Control of Bow Leg Hopping Robot;" The robotics Institute; Carnegie Mellon University; Pittsburgh, PA 15213, USA; 6 pages.			
/MW/		Buehler; "Dynamic Locomotion with One, Four and Six-Legged Robots;" Ambulatory Robatics Laboratory, Centre for Intelligent Machines; McGill University; Montreal, Quebec, Canada, H3A 2A7; www.cim.mcgill.ca/~artweb; pages 1-6.			
/MW/		Zeglin; "The Bow Leg Hopping Robot;" CMU-RI-TR-99-33; The Robotics Institute; Carnegle Mellon University; Pittsburgh, PA; October 21, 1999; pages 1-161.			
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